

Actuator MK41



MK41 is a compact, high-load electric actuator specifically designed for ultra-low adjustable beds or nursing beds, providing a stable thrust of up to 8,000N. It is particularly suitable for beds with extremely low ground clearance, enhancing care safety and product flexibility. It is widely applicable in a variety of applications, including hospitals, long-term care facilities, and home care.

Features and Options

• Main applications: Medical care

• Input voltage: 24V DC

• Max. load: 8000N (Push) / 4000N (Pull)

Self-locking ability: 6500N

• Max. speed at no load: 8.3mm/sec

Stroke: 50~300mmNoise level: ≦50dB

• IP Protection level: IPX6 (static, non-action)

• Color: Light gray RAL 7035

Optional positioning signal feedback with hall effect sensor x 2

Optional mechanical push only extension tube

Optional safety nut (in push direction)

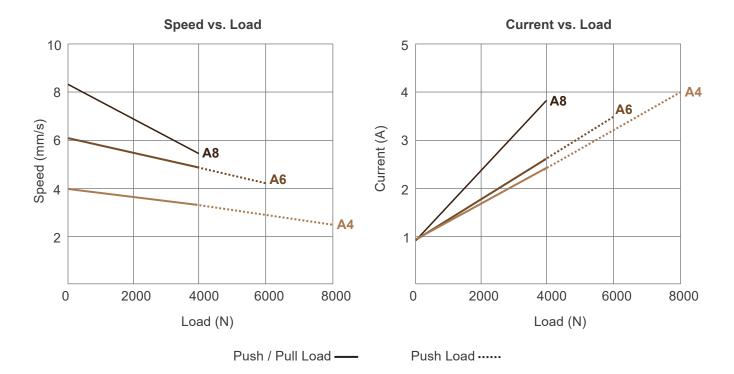
Optional mechanical brake

Usages

- Duty cycle: 10%, max. 2 min. continuous operation in 20 min.
- Operating ambient temperature: +5°C to +40°C
- Transport and storage temperature: -10°C to +50°C
- Relative humidity: 20% to 85%
- Atmospheric pressure: 71 kPa to 101.3 kPa
- Height above mean sea level: Max. 3,000 meters

Performance Data

Model No.	Push	Pull	*Self-locking	*Typical Speed (mm/s)		*Typical Current (A)	
Wodel No.	Max.(N)	Max.(N)	ability (N)	No load	Full load	No load	Full load
MK41-24 A4	8000	4000	6500	4.0	2.7	0.9	4.0
MK41-24 A6	6000	4000	5500	6.1	4.3	0.9	4.5
MK41-24 A8	4000	4000	4000	8.3	5.7	0.9	3.8



*Remarks:

- 1. The self-locking ability is performed by short circuit the motor terminals when the actuator is stopped. All MOTECK compatible control boxes are designed with this feature.
- 2. For A4 and A6 models requiring greater self-locking capability, select the brake option to prevent slipping within the rated load range.
- 3. The typical speed or typical current means the average value neither upper limit nor lower limit. The performance curves are made with typical values.

Inrush current



- When the actuator starts to operate, an inrush current of about 0.2 seconds will be generated. The starting inrush current of MK41 can reach about 3 times of the typical current under the actuator load.
- If a circuit board power supply is used, the specifications must be sufficient to handle the inrush current. If batteries are used as the power source, inrush current will not be a problem.
- MOTECK controllers are designed to take into account the inrush current when the
 actuator starts. If the user provides his or her own controller, this feature must be
 considered in the specifications and protection mechanisms. Besides, the
 connectors, switches and relays selected by users must also be able to withstand
 the starting currents.

Dimensions

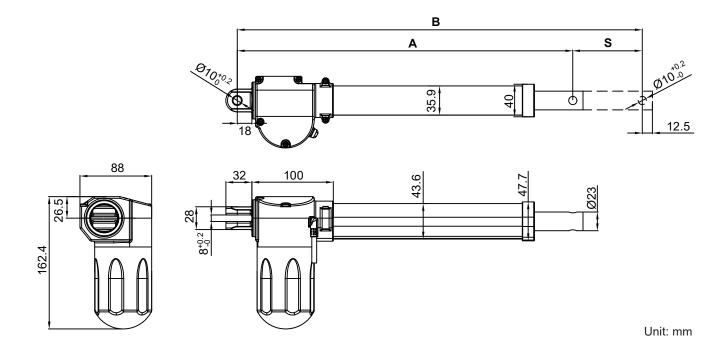
1. Installation dimension

• Retracted length (A)

Front connector	Retracted length (A)	Safety option	
3	A≧S+160mm (±3mm)	+8mm	
8	A≧S+188mm (±3mm)	TOITIIT	

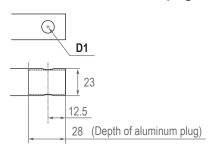
- Available stroke (S) range = 50 ~ 300mm
- Extended length (B) = Retracted length (A) + Stroke (S)

2. Drawing

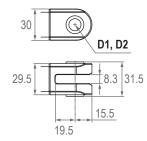


3. Front connector

3: Drilled hole with aluminum plug



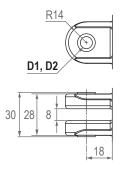
8: Aluminum alloy clevis



Front connector code	Diameter of pivot without bushing (D1)	Diameter of pivot with bushing (D2)
3	ø10	N/A
8	ø10, ø12	ø8, ø10

4. Rear connector

1: Aluminum alloy clevis

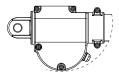


Unit: mm

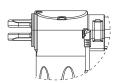
Rear connector code	Diameter of pivot without bushing (D1)	Diameter of pivot with bushing (D2)		
1	ø10, ø12	ø8, ø10		

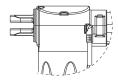
5. Pivot orientation of rear connectors

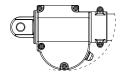
0:0° (standard)









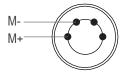


Compatibility

Product	Model	MK41 spec	
Control box	CM45	MOTECK H-type 4-pin DIN plug	
	CM41	Without positioning feedback MOTECK LR-type 6-pin minifit plug	
	CM41-M, CB5P-M	With dual Hall effect sensors for positioning MOTECK LR-type 6-pin minifit plug	

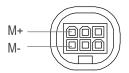
Cable Plug

• MOTECK H-type plug



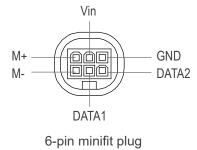
4-pin DIN plug

- MOTECK LR-type plug
 - Without positioning feedback



6-pin minifit plug

- With dual Hall effect sensors for positioning







LR-type

• Note:

	Definition	Comments			
Power	M+ M-	Connect blue wire to "Vdc +" & Brown wire to "Vdc -" of DC power			
	•••	to extend the actuator. Switch the polarity of DC input to retra			
	Vin	Voltage input range (Vin): 5 ~ 20V			
		High= Input - 1.2V (±0.6V) Low= GND Hall signal data:			
0: 1	Hall 1 output	High Low Hall 1 High Low Hall 2 Low Hall 2			
Signal		Actuator extends Actuator retracts			
		Hall effect sensor resolution:			
		Model No. Resolution (pulses/mm)			
	Hall 2 output	MK41-24A4-XXX.XXX-XXXXXXX 10.00			
		MK41-24A6-XXX.XXX-XXXXXXXXXXXXXXXXXXXXXXXXXXXXX			
		MK41-24A8-XXX.XXX-XXXXXXX 5.00			
	GND				

Ordering Key

