Actuator
LD3

LD3 features its compact design, which is suitable for various applications that require limited installation space, such as window or gate opener, adjustable seat tilting and medical devices.

Features and Options

Main applications: Industrial, Furniture, Home care, Medical

Standard features:

- Input voltage: 12V DC / 24V DC
- Max. load: 1000N (Push / Pull)
- Max. static load: 2500N (Push / Pull)
- Speed at no load: 43.9mm/sec (typical value)
- Speed at full load: 5.5mm/sec (typical value @1000N loaded)
- Stroke: 50 / 100 / 150 / 200 / 250 / 300mm
- Noise level: Please refer to Performance Data
- IP level: IP54
- Preset limit switches
- Duty cycle: 25%, max. 1 min. continuous operation in 4 min.
- Operating ambient temperature: -25°C ~ +65°C
- Certified: CE Marking, Electromagnetic Compatibility Directive 2014/30/EU (for LD3 only)

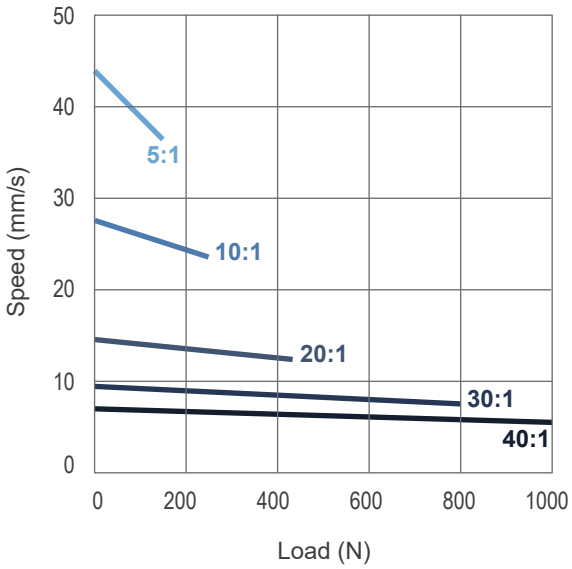
Options:

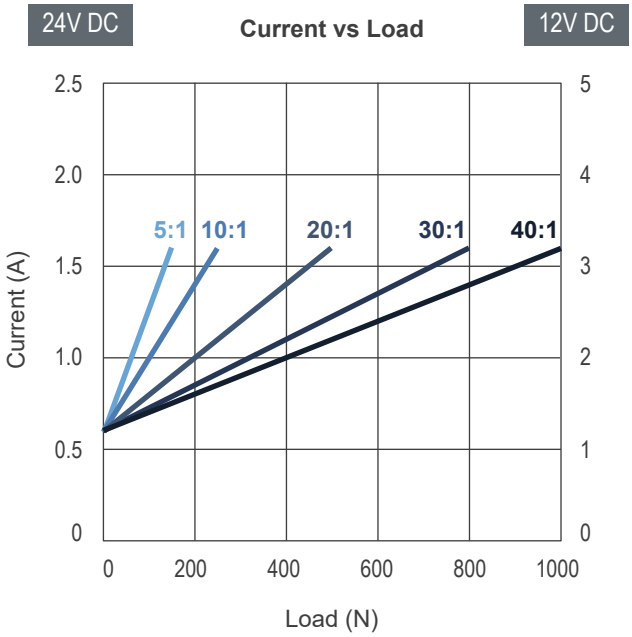
- Medical version (LD3M, compliance with EN 60601)
- Quiet version (LD3Q, noise level ≦55dB)
- Positioning signal feedback with Hall effect sensor x 1
- Positioning signal feedback with Hall effect sensor x 2
- Analog positioning feedback with Potentiometer (POT)
- IP level: IP65
- C15 clamp: An alternative part to hold the actuator
- MB22 mounting bracket

Performance Data

Regular version (LD3)

Model No.	Gear Ratio	Push / Pull Max. (N)	Self-locking force Max. (N)	* Typical Speed (mm/s)		* Typical Current (A)				Noise Level (dB)
				No Load	Full Load	No Load		Full Load		
						24V	12V	24V	12V	
LD3-XX-05-K3...	5:1	150	2500	43.9	36.5	0.6	1.2	1.6	3.2	≦70
LD3-XX-10-K3...	10:1	250	2500	27.6	23.5	0.6	1.2	1.6	3.2	≦70
LD3-XX-20-K3...	20:1	500	2500	14.6	12.3	0.6	1.2	1.6	3.2	≦70
LD3-XX-30-K3...	30:1	800	2500	9.5	7.5	0.6	1.2	1.6	3.2	≦70
LD3-XX-40-K3...	40:1	1000	2500	7.0	5.5	0.6	1.2	1.6	3.2	≦70





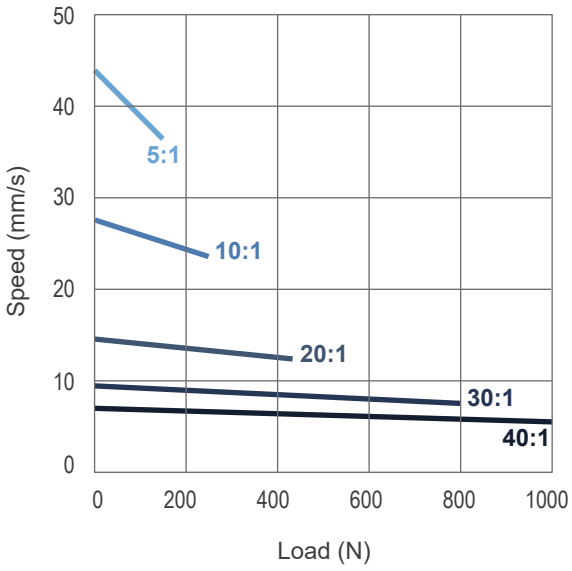
Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit. The performance curves are made with typical values.

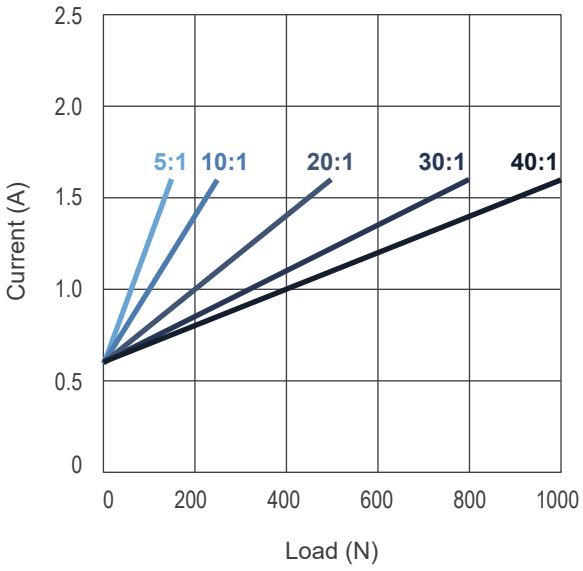
Medical version (LD3M)

Model No.	Gear Ratio	Push / Pull Max. (N)	Self-locking force Max. (N)	* Typical Speed (mm/s)		* Typical Current (A) @24V DC		Noise Level (dB)
				No Load	Full Load	No Load	Full Load	
LD3M-XX-05-K3...	5:1	150	2500	43.9	36.5	0.6	1.6	≦70
LD3M-XX-10-K3...	10:1	250	2500	27.6	23.5	0.6	1.6	≦70
LD3M-XX-20-K3...	20:1	500	2500	14.6	12.3	0.6	1.6	≦70
LD3M-XX-30-K3...	30:1	800	2500	9.5	7.5	0.6	1.6	≦70
LD3M-XX-40-K3...	40:1	1000	2500	7.0	5.5	0.6	1.6	≦70

Speed vs Load



Current vs Load

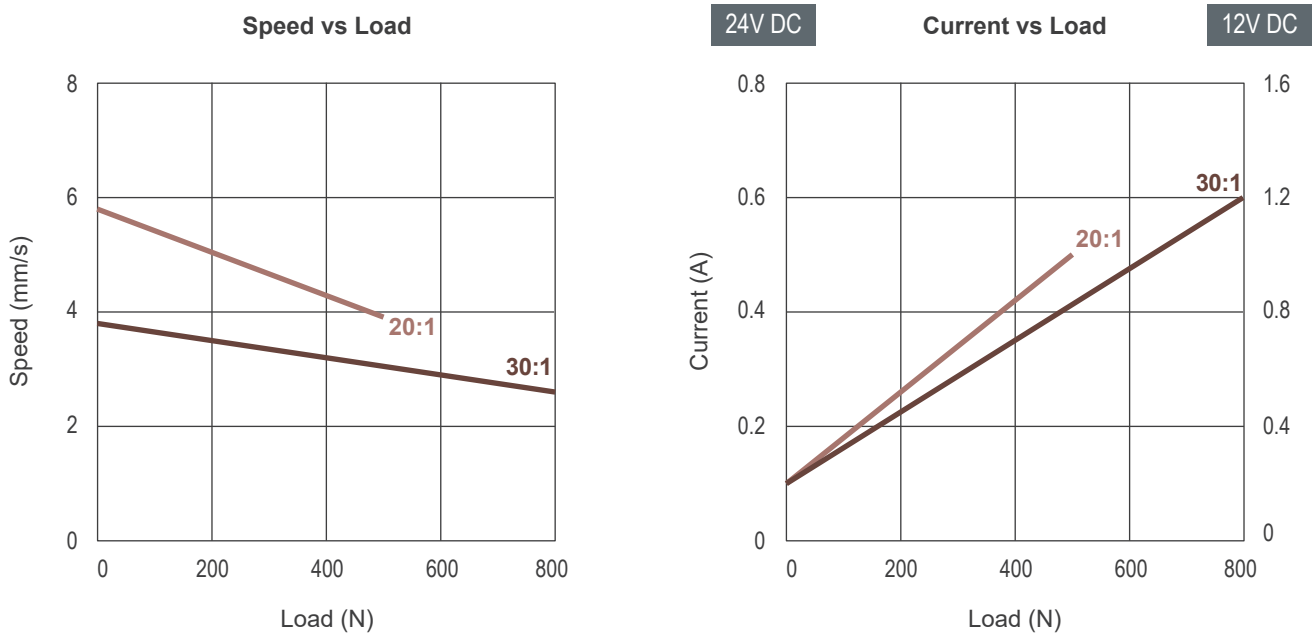


Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit.
The performance curves are made with typical values.

Quiet version (LD3Q)

Model No.	Gear Ratio	Push / Pull Max. (N)	Self-locking force Max. (N)	* Typical Speed (mm/s)		* Typical Current (A)				Noise Level (dB)
				No Load	Full Load	No Load		Full Load		
						24V	12V	24V	12V	
LD3Q-XX-20-D3...	20:1	500	2500	5.8	3.9	0.1	0.2	0.5	1.0	≦55
LD3Q-XX-30-D3...	30:1	800	2500	3.8	2.6	0.1	0.2	0.6	1.2	≦55



Remarks:

* The typical speed or typical current means the average value neither upper limit nor lower limit. The performance curves are made with typical values.

Dimensions

Extended length (B) = Retracted length (A) + Stroke (S)
Retracted length (A)

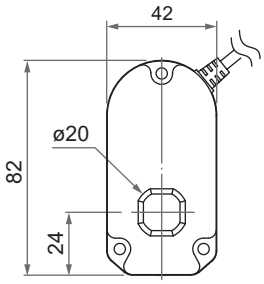
Option	Front connector code	Stroke (S)					
		50	100	150	200	250	300
Basic or with Hall sensor	1	158	209	260	311	362	413
	3	199	250	301	352	403	454
	6	168.5	219.5	270.5	321.5	372.5	423.5
With POT	1	195	246	297	348	399	450
	3	236	287	338	389	440	491
	6	205.5	256.5	307.5	358.5	409.5	460.5

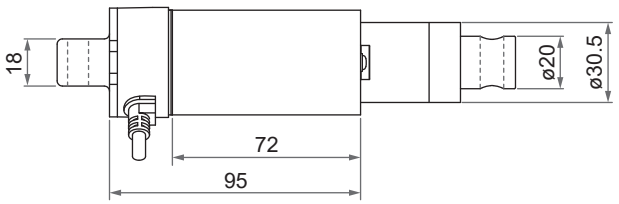
(tolerance: ±3mm)

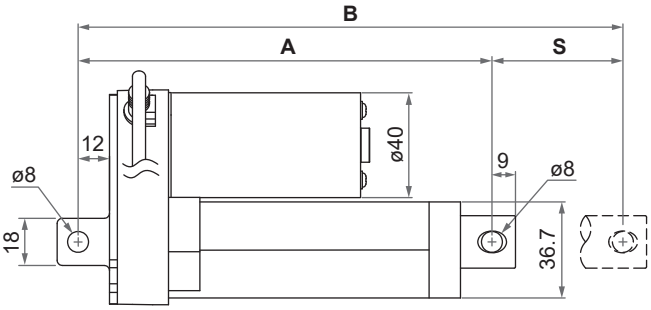
Note: The dimension “A” is shown in page 5 & 6, as indicated in the figure below.

Drawing

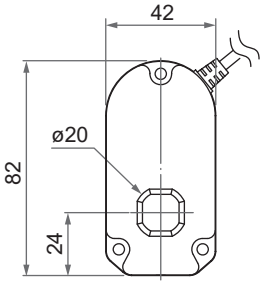
- **Regular version (LD3) & Quiet version (LD3Q)**
  - Basic, without positioning feedback.

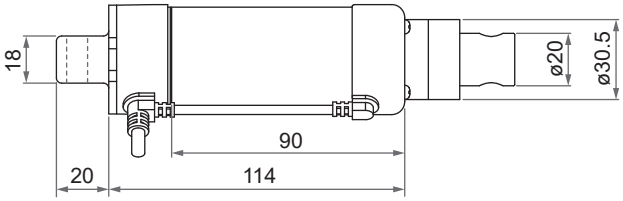


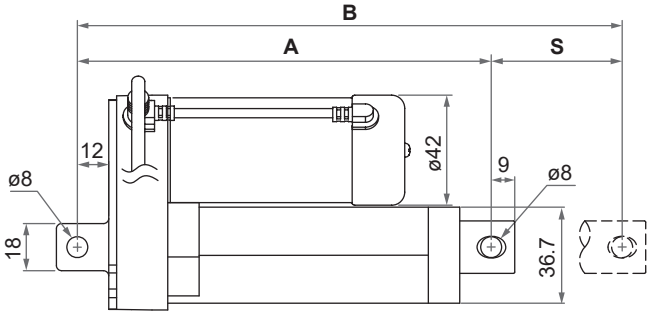




  - With Hall effect sensor positioning feedback



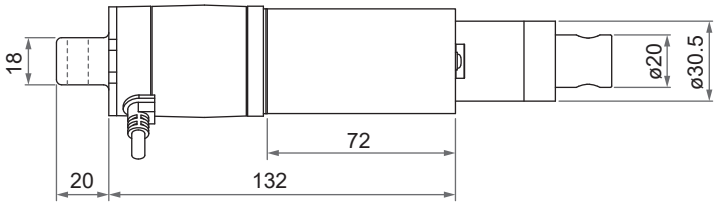


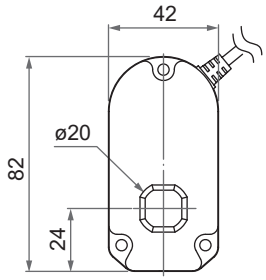


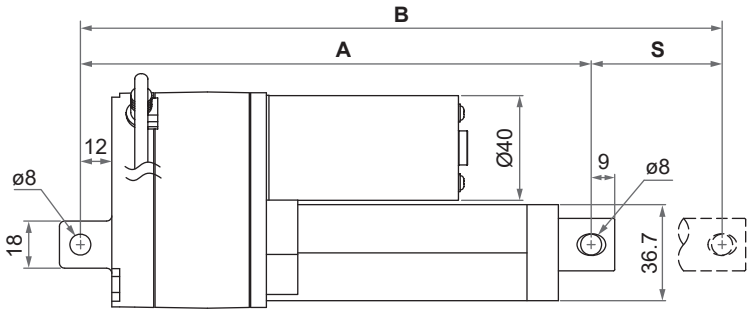
Note: As an example in 0° orientation for rear connector.

Unit: mm

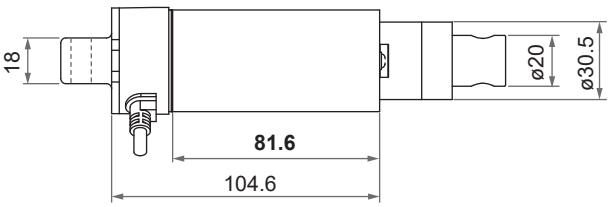
- With potentiometer (POT) absolute positioning feedback

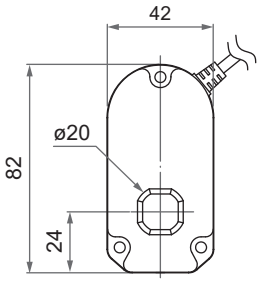


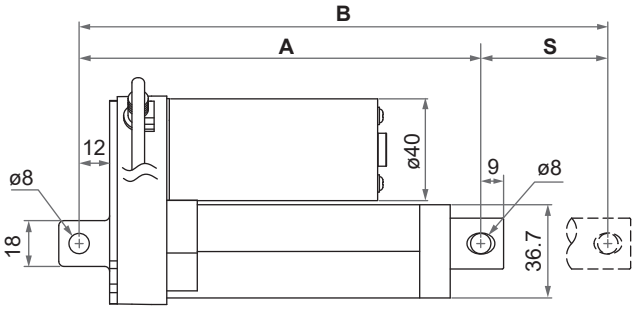




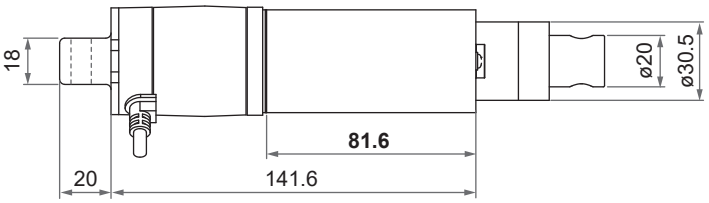
- **Medical version (LD3M)**
  - Basic, without positioning feedback

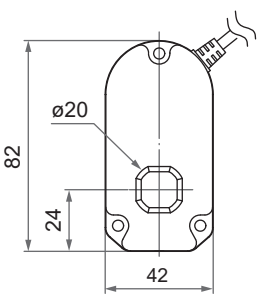


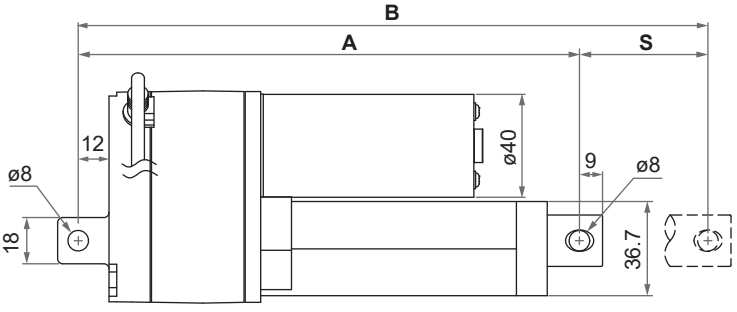




- With potentiometer (POT) absolute positioning feedback





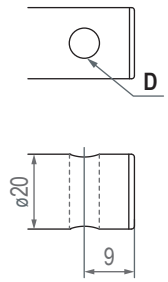


Note: As an example in 0° orientation for rear connector.

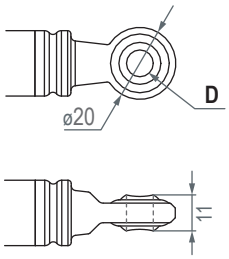
Unit: mm

- **Front connector**

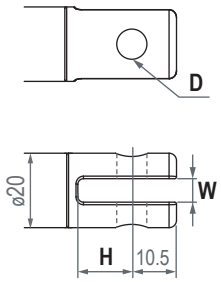
1: Drilled hole



3: Spherical rod eye



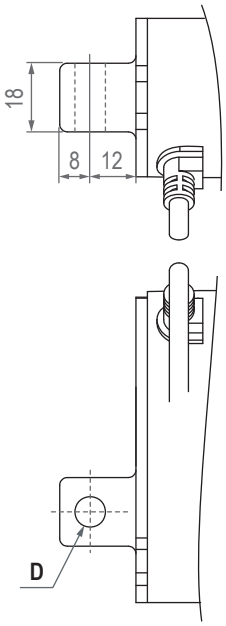
6: Plastic slot



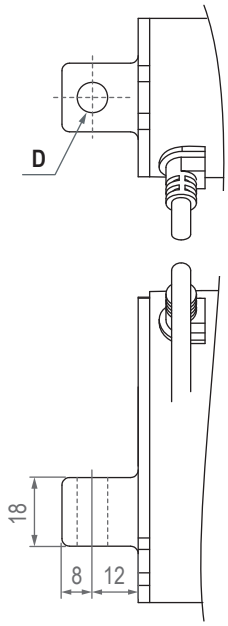
Front connector code	Diameter of pivot without bushing (D)	Slot width (W)	Slot depth (H)
1	ø6.4, ø8, ø10	N/A	N/A
3	ø8	N/A	N/A
6	ø8, ø10	6	15

- **Rear connector**

1: Zinc alloy clevis, 0°



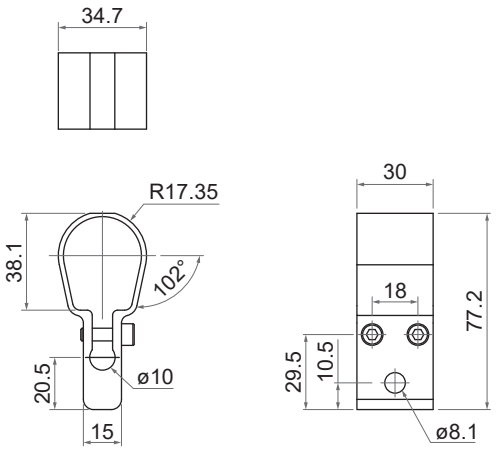
3: Zinc alloy clevis, 90°



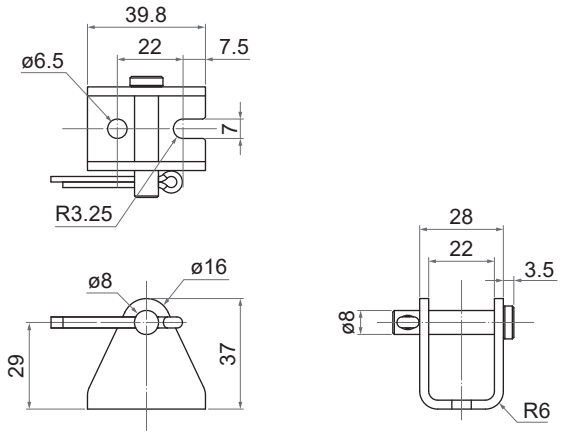
Rear connector code	Diameter of pivot without bushing (D)	Slot width (W)	Slot depth (H)
1, 3	ø6.4, ø8, ø10	N/A	N/A

Unit: mm

- **C15 clamp**



- **MB22 mounting bracket**



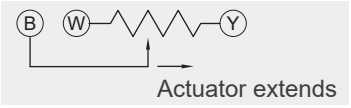
Unit: mm

Wiring

- **Basic, without positioning feedback.**

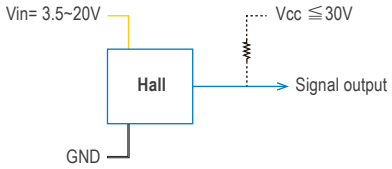
	Wire color	Definition	Descriptions
Power wires	Red	DC power	Connect red wire to “Vdc +” & black wire to “Vdc -“ of DC power to extend the actuator. Switch the polarity of DC input to retract it.
	Black		

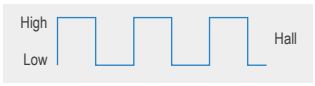
- **With potentiometer (POT) absolute positioning feedback**

<table>
<tr><th></th><th>Wire color</th><th>Definition</th><th>Descriptions</th></tr>
<tr><td rowspan="2">Power wires</td><td>Red</td><td rowspan="2">DC power</td><td rowspan="2">Connect red wire to “Vdc +” & black wire to “Vdc -“ of DC power to extend the actuator. Switch the polarity of DC input to retract it.</td></tr>
<tr><td>Black</td></tr>
<tr><td rowspan="4">Signal wires</td><td>Yellow</td><td>Vin</td><td>Input voltage 70V max.</td></tr>
<tr><td>Blue</td><td>POT output</td><td>1. Potentiometer specification:
- 10K ohm, 10 turns.
- Tolerance ±5%
2. Output voltage: The voltage (resistance) between Blue and White increases linearly from about 0 when the actuator extends, and decreases when it retracts.
 

3. There are different resolutions according to the stroke length (as table below)
<table><tr><th>Stroke</th><th>Resistance (tolerance: ±0.3KΩ)</th></tr><tr><td>50mm</td><td>0.3 ~ 9.3K</td></tr><tr><td>100mm</td><td>0.3 ~ 9.7K</td></tr><tr><td>150mm</td><td>0.3 ~ 8.6K</td></tr><tr><td>200mm</td><td>0.3 ~ 9.6K</td></tr><tr><td>250mm</td><td>0.3 ~ 9.3K</td></tr><tr><td>300mm</td><td>0.3 ~ 9.3K</td></tr></table></td></tr>
<tr><td>White</td><td>GND</td><td></td></tr>
</table>

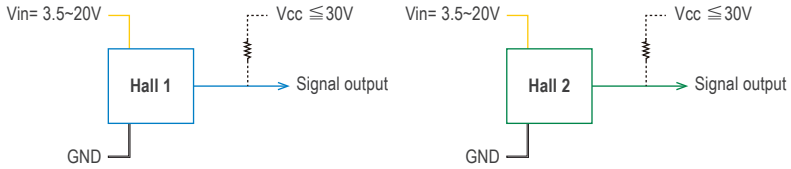
- **With single Hall effect sensor positioning feedback**

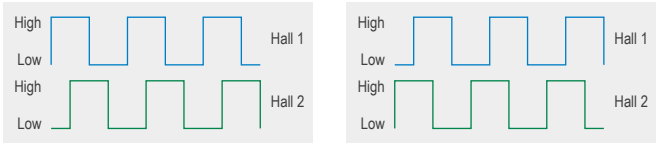
<table>
<tr><th></th><th>Wire color</th><th>Definition</th><th>Descriptions</th></tr>
<tr><td rowspan="2">Power wires</td><td>Red
Black</td><td>DC power</td><td>Connect red wire to “Vdc +” & black wire to “Vdc -“ of DC power to extend the actuator. Switch the polarity of DC input to retract it.</td></tr>
<tr><td rowspan="3">Signal wires</td><td>Yellow</td><td>Vin</td><td>Voltage input range: 3.5 ~ 20V</td></tr>
<tr><td>Blue</td><td>Hall output</td><td>The signal wires output should connect the pull-up resistor to the operating voltage (Vcc) of the system. (10KΩ resistor is recommended)
Wiring:
 

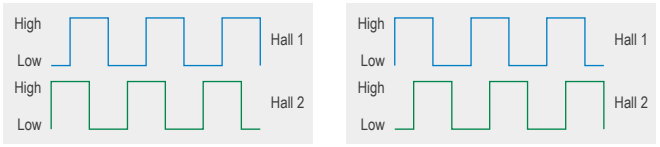
High= Determined by Vcc and the pull-up resistor.
Hall signal data:
 

Hall effect sensor resolution:
<table>
<tr><th>Gear ratio</th><th>Resolution (pulses/mm)</th></tr>
<tr><td>5:1</td><td>2.27</td></tr>
<tr><td>10:1</td><td>3.62</td></tr>
<tr><td>20:1</td><td>6.86</td></tr>
<tr><td>30.1</td><td>10.57</td></tr>
<tr><td>40:1</td><td>14.27</td></tr>
</table></td></tr>
<tr><td>White</td><td>GND</td><td></td></tr>
</table>

- **With dual Hall effect sensors positioning feedback**

<table>
<tr><th></th><th>Wire color</th><th>Definition</th><th>Descriptions</th></tr>
<tr><td rowspan="2">Power wires</td><td>Red
Black</td><td>DC power</td><td>Connect red wire to “Vdc +” & black wire to “Vdc -“ of DC power to extend the actuator. Switch the polarity of DC input to retract it.</td></tr>
<tr><td rowspan="4">Signal wires</td><td>Yellow</td><td>Vin</td><td>Voltage input range: 3.5 ~ 20V</td></tr>
<tr><td>Blue</td><td>Hall 1 output</td><td rowspan="2">The signal wires output should connect the pull-up resistor to the operating voltage (Vcc) of the system. (10KΩ resistor is recommended)
Wiring:
 

High= Determined by Vcc and the pull-up resistor.
Hall signal data:
- A type
 

- B type
 

Hall effect sensor resolution:
<table>
<tr><th>Gear ratio</th><th>Resolution (pulses/mm)</th><th>Hall signal data type</th></tr>
<tr><td>5:1</td><td>2.27</td><td>B type</td></tr>
<tr><td>10:1</td><td>3.62</td><td>A type</td></tr>
<tr><td>20:1</td><td>6.86</td><td>A type</td></tr>
<tr><td>30.1</td><td>10.57</td><td>A type</td></tr>
<tr><td>40:1</td><td>14.27</td><td>B type</td></tr>
</table></td></tr>
<tr><td>Green</td><td>Hall 2 output</td></tr>
<tr><td>White</td><td>GND</td><td></td></tr>
</table>

Ordering Key

Regular version

LD3 - 24 - 10 - K3 - 100 - C 1 1 - HS2 - 54 - M2 - C

Input voltage	**12**: 12V DC **24**: 24V DC
Gear type *(Refer to Page 2)*	**05, 10, 20, 30, 40**
Motor and Spindle type	**K3**: 6000rpm / 3mm pitch
Stroke	**050**: 50mm **100**: 100mm **150**: 150mm **200**: 200mm **250**: 250mm **300**: 300mm
Front connector *(Refer to Page 7)*	**1**: Drilled hole **3**: Spherical rod eye **6**: Plastic slot
Rear connector *(Refer to Page 7)*	**1**: Zinc alloy clevis, 0° **3**: Zinc alloy clevis, 90°
Positioning feedback	**Blank**: Basic, without positioning feedback. **HS1**: Hall effect sensor x 1 **HS2**: Hall effect sensor x 2 **POT**: Potentiometer (POT)
IP level	**54**: IP54 (standard) **65**: IP65
MB22 mounting bracket *(Refer to Page 8)*	**Blank**: None **M1**: MB22 mounting bracket x 1 **M2**: MB22 mounting bracket x 2
C15 clamp *(Refer to Page 8)*	**Blank**: None **C**: C15 clamp

Medical version

LD3M - 24 - 10 - K3 - 100 - C 1 1 - POT - 65 - M2 - C

Input voltage	**24**: 24V DC
Gear type *(Refer to Page 3)*	**05, 10, 20, 30, 40**
Motor and Spindle type	**K3**: 6000rpm / 3mm pitch
Stroke	**050**: 50mm **100**: 100mm **150**: 150mm **200**: 200mm **250**: 250mm **300**: 300mm
Front connector *(Refer to Page 7)*	**1**: Drilled hole **3**: Spherical rod eye **6**: Plastic slot
Rear connector *(Refer to Page 7)*	**1**: Zinc alloy clevis, 0° **3**: Zinc alloy clevis, 90°
Positioning feedback	**Blank**: Basic, without positioning feedback. **POT**: Potentiometer (POT)
IP level	**54**: IP54 (standard) **65**: IP65
MB22 mounting bracket *(Refer to Page 8)*	**Blank**: None **M1**: MB22 mounting bracket x 1 **M2**: MB22 mounting bracket x 2
C15 clamp *(Refer to Page 8)*	**Blank**: None **C**: C15 clamp

Quiet version

LD3Q - 24 - 20 - D3 - 100 - C 1 1 - HS2 - 54 - M2 - C

Input voltage	**12**: 12V DC **24**: 24V DC
Gear type *(Refer to Page 4)*	**20, 30**
Motor and Spindle type	**D3**: 2400rpm / 3mm pitch
Stroke	**050**: 50mm **100**: 100mm **150**: 150mm **200**: 200mm **250**: 250mm **300**: 300mm
Front connector *(Refer to Page 7)*	**1**: Drilled hole **3**: Spherical rod eye **6**: Plastic slot
Rear connector *(Refer to Page 7)*	**1**: Zinc alloy clevis, 0° **3**: Zinc alloy clevis, 90°
Positioning feedback	**Blank**: Basic, without positioning feedback. **HS1**: Hall effect sensor x 1 **HS2**: Hall effect sensor x 2 **POT**: Potentiometer (POT)
IP level	**54**: IP54 (standard) **65**: IP65
MB22 mounting bracket *(Refer to Page 8)*	**Blank**: None **M1**: MB22 mounting bracket x 1 **M2**: MB22 mounting bracket x 2
C15 clamp *(Refer to Page 8)*	**Blank**: None **C**: C15 clamp

Certifications

Regular version

LD3 actuator is compliant with the following regulations, in terms of the essential conformity requirements of EMC Directive of 2014/30/EU.

Emission	Immunity
EN55014-1:2017+A11:2020	EN 55014-2:2015