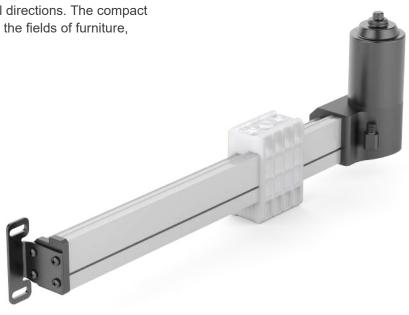


# Actuator **BD62**

BD62 belongs to the design concept of slider-type linear motion, which can obtain a larger stroke with a smaller installation size, and can be applied in both push and pull directions. The compact size design is an ideal driving solution in the fields of furniture, home care and fitness equipment.



## **Features and Options**

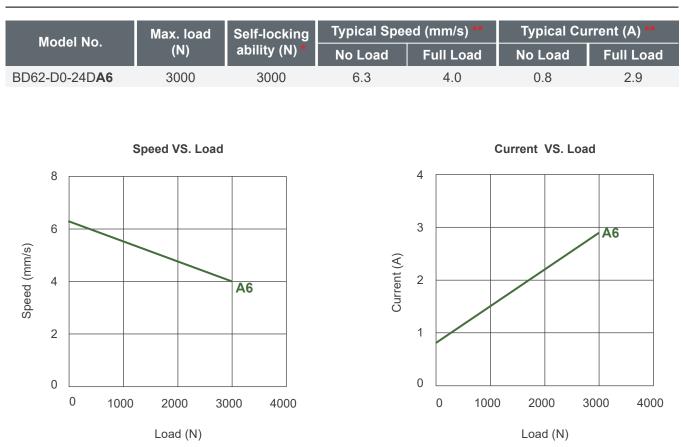
**Main applications:** Furniture, Home care and Fitness equipment **Standard features:** 

- Input voltage: 24V DC
- Max. load: 3000N (Push / Pull)
- Max. speed at no load: 6.2mm/sec (Typical value)
- Speed at full load: 3.8mm/sec (Typical value @3000N loaded)
- ullet Stroke: 100  $\sim$  1000mm
- Noise level: ≦55dB
- Preset limit switches
- Front end cover has the metal plate for fixing
- Duty cycle: 10%, max. 2 min. continuous operation in 20 min.
- ullet Operating ambient temperature: -20°C  $\sim$  +65°C

#### **Options:**

• Positioning signal feedback with Hall effect sensor x 2

## **Performance Data**

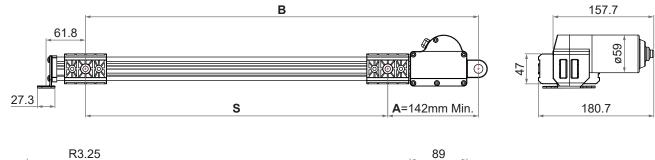


#### Remarks:

- \* The self-locking ability is performed by short circuit the motor terminals when the actuator is powered off. All MOTECK compatible control boxes are designed with this feature. Mechanical brake in push direction is available upon request, to further enhance the self-locking ability to maximum load.
- \*\* The typical speed or typical current means the average value neither upper limit nor lower limit, which measured under room temperature and stable power. The performance curves are made with typical values.

## Dimensions

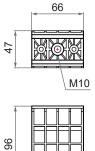
- $\bullet$  Available stroke (S) range = 100  $\sim$  1000mm
- Extended length (B) = Retracted length (A) + Stroke (S)
- Retracted length (A) = 142mm Min. (±3mm)
- Drawing





#### • Front connector

D: D-type plastic slider block





0: Plastic





Unit: mm

# Compatibility

| Product   | Model   | BD62 spec   |
|---|---|---|
| Control box   | T-control, CS1, CS2, CB3T, CB4M, CBT2           | <ul><li>Without positioning sensor</li><li>With Moteck F-type 4-pin DIN plug</li></ul>                            |
|   | CF11H, CF12H                                    | <ul><li>Without positioning sensor</li><li>With Moteck L3-type minifit 6-pin plug</li></ul>                       |
|   | CB3T-SY, CB4M-S, CB4M-B                         | <ul> <li>With dual Hall effect sensors for positioning</li> <li>With Moteck F-type 6-pin DIN plug</li> </ul>      |
|   | CF11S, CF12S                                    | <ul> <li>With dual Hall effect sensors for positioning</li> <li>With Moteck L3-type minifit 6-pin plug</li> </ul> |
| Hand control  | Depend on control box                           | • Powered by control box  |
|   | HS15  | • With Moteck S-type DIN 41529 male plug <sup>(1)</sup>   |
|   | HB, TPSL,<br>HS02, HZ02, HZ03, HZ04, HZ05, HZ06 | • With Moteck direct-cut power cable DL1 <sup>(2)</sup>   |
| Accessory Power adapter:<br>DPA-58-2920-C8 (formerly TSW1),<br>DPA-87-2930-C6 (formerly TSW3),<br>WPA-29-2910-NA (formerly TSW4),<br>DPA-87-2930-C8 |   | • With Moteck direct-cut power cable DL1  |

### Remarks:

(1) The S-type DIN 41529 plug of the actuator is connected to the HS15 hand control directly, no control box.

(2) The actuator is connected to the hand control through the DL1 cable directly, no control box.

# Cable Plug

## A. Connecting control devices that provide power

|                                   | Without positioning feedback | Positioning feedback with<br>dual Hall effect sensors |
|-----------------------------------|------------------------------|---|
| Moteck F-type DIN male plug       | M-<br>M+<br>4p2c             | GND Hall 2<br>M- Vin<br>M+ Hall 1<br>6p6c             |
|                                   |                              |   |
| Moteck L3-type Minifit male plug  | M-                           | M-<br>M+<br>Hall 2<br>Hall 1<br>6p6c                  |
|                                   |                              |   |
|                                   | M M+                         | N/A   |
| Moteck S-type DIN 41529 male plug | 2p2c                         |   |

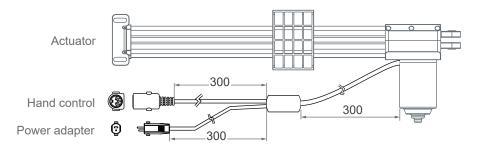
## Note: Pin definition

|        | Definition       | Descriptions  |  |  |
|--------|------------------|---|--|--|
| Power  | M+               | Connect M+ to "Vdc +" & M- to "Vdc -" of DC power to extend the actuator.<br>Switch the polarity of DC input to retract it. |  |  |
|        | M-               |   |  |  |
|        | Vin              | Voltage input range: 5 ~ 20V  |  |  |
| Signal | Hall 1<br>output | High= Input - 1.2V (±0.6V)<br>Low= GND<br>Hall signal data:   |  |  |
|        | Hall 2<br>output | High High Hall 2 Low Actuator retracts  |  |  |
|        |                  | Hall effect sensor resolution: 6.667 pulses/mm  |  |  |
|        | GND              |   |  |  |

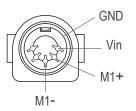
## B. Connecting control devices that DO NOT provide power

### 1. Cable solution

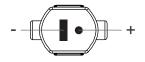
• With direct-cut power cable DL1



- 2. Hand control connector: Moteck U-type DIN 5-pin female connector
  - 1 drive



- **Note:** Connect M1+ to "Vdc +" & M1- to "Vdc -" of DC power to extend the M1 actuator. Switch the polarity of DC input to retract it.
- 3. Power connector: Moteck S-type DIN 41529 2-pin male plug





U-type female connector



S-type male plug

# Cable with Flying Leads

## • Basic, without positioning feedback.

|       | Wire color | Definition | Descriptions   |
|-------|------------|------------|--|
| Power | White      | DC Power   | Connect white wire to "Vdc +" & black wire to "Vdc -" of DC power      |
| wires | Black      |            | to extend the actuator. Switch the polarity of DC input to retract it. |

## With dual Hall effect sensors for positioning

|                 | Wire color | Definitions      | Descriptions   |  |
|-----------------|------------|------------------|--|--|
| Power<br>wires  | Blue       | DC Power         | Connect blue wire to "Vdc +" & brown wire to "Vdc -" of DC power   |  |
|                 | Brown      |                  | to extend the actuator. Switch the polarity of DC input to retract it.                                     |  |
| Signal<br>wires | Yellow     | Vin              | Voltage input range: 5 ~ 20V   |  |
|                 | Red        | Hall 1<br>output | High= Input - 1.2V (±0.6V)<br>Low= GND<br>Hall signal data:  |  |
|                 | Green      | Hall 2<br>output | High<br>Low Hall 2<br>Actuator extends Actuator retracts<br>Hall effect sensor resolution: 6.667 pulses/mm |  |
|                 | Black      | GND              |  |  |

# Ordering Key

|  | BD62 - D 0 - 24 D A6 - 157 . 0612 - H 0 R 0  |
|--|--|
| Front connector<br>(Refer to Page 3)       | D: D-type plastic slider block   |
| Rear connector<br>(Refer to Page 3)        | 0: Plastic   |
| Input voltage                              | 24: 24V DC   |
| Motor                                      | D: Default motor   |
| Motor and spindle type                     | A6: 2500rpm / 6mm pitch  |
| Retracted length<br>(Refer to Page 3)      | xxx  |
| Extended length<br>(Refer to Page 3)       | xxxx   |
| Positioning<br>feedback                    | 0: None<br>H: Dual Hall effect sensors   |
| Reserved                                   | 0  |
| Location of cable outlet (Refer to Page 6) | R: Rear end  |
| Cable                                      | <ul> <li>0: 300mm straight</li> <li>1: 1000mm straight</li> <li>2: 450mm with 300mm coiled</li> <li>A: Direct-cut power cable DL1 (Refer to Page 6)</li> </ul> |



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